Required Problems

1. Recall the binary search tree data type from lecture (see the end of the lecture notes on April 3). We coded the functions singleton, find, and insert, as well as exploring functors and fmap on this structure.

   For this problem, finish the binary search tree implementation and code the function `removeFromTree`. Recall that you delete in a binary search tree as follows

   - if the node to be deleted is a leaf, simply replace it with an EmptyTree (which is basically a null).
   - if the node to be deleted has only one child, you can delete this value and promote the child to its place.
   - if the node to be deleted has two children, you need to find the next node in an in order traversal of the tree, remove it, and move its value up to take the place of the deleted node.

   Hint: The easiest way to find the next node in an in order traversal of the tree is to realize that it is the smallest element in the subtree rooted at the node's right child. So code a helper function `findMin` which finds the minimum element in a binary search tree, and use it on the right child to find which node to use when replacing yourself. (And don’t forget to delete that minimum node, also.)

2. For this problem, you will write a module that holds sets over a type `a`. Our goal is to represent the set as a sorted list with NO repeated elements. Therefore, the type `a` will always be of the classes:

   - `Eq`: so that `==` and `/=` are defined for elements of type `a`
   - `Ord`: so that we can compare using `<`, etc.
   - `Enum`: So that we can make lists of the form `[x..y]` where `x` and `y` are elements of type `a`.
   - `Bounded`: so that `minBound::a` and `maxBound::a` are the smallest and largest elements of `a`.

   (Note that this means we can form `[minBound..maxBound]::[a]`, a list of all the elements of `a`.)

   So our declaration of the Set type is:

   ```haskell
   data Set a = Set [a]
               deriving (Show, Eq, Ord)
   ```

   ```haskell
   ```
I also have 2 functions that let you go back and forth between sets and lists, primarily for testing purposes. You need to import Data.List for these to work, so I’m giving the syntax for that below:

```haskell
import qualified Data.List as L

list2set :: Ord a => [a] -> Set a
list2set = Set . L.nub . L.sort

set2list :: Set a -> [a]
set2list (Set xs) = xs
```

The temptation in implementing the set operations below is the overrely on list2set which results in code that is simple, clear, and slow!! For example, for the union operation we could define:

```haskell
unionS_slow :: (Ord a) => Set a -> Set a -> Set a
unionS_slow (Set xs) (Set ys) = list2set (xs ++ ys)
```

The problem is that this will result in worst case $O(n^2)$ running time (where $n$ is the max of the length of the 2 sets) and this is much too slow. To speed things up, we need to take advantage of the fact that the lists are sorted and have no repeat elements. So a much better implementation of union is the following, which has a $O(n)$ running time:

```haskell
unionS :: (Ord a) => Set a -> Set a -> Set a
unionS (Set xs) (Set ys) = Set $ merge xs ys
  where
    merge [] ys = ys
    merge xs [] = xs
    merge (x:xs) (y:ys)
      | x<y = x:merge xs (y:ys)
      | x>y = y:merge (x:xs) ys
      | otherwise = x:merge xs ys
```

Note that on any of these problems, I will be looking for (at worst) an $O(n)$ running time, so be careful about using list2set! In particular, you don’t want to use those for intersectS or diffS.

(a) Write two functions:

```haskell
singS :: a -> Set a
emptyS :: Set a
```

which (respectively) create a single element set of the input and an empty set.

(b) Write the function:
addToS :: (Ord a) => a -> Set a -> Set a

so that the first input will be added to the set in the appropriate location.

(c) Write the function:

intersectS :: (Ord a) => Set a -> Set a -> Set a

so that \textit{intersectS} \ s1 \ s2 returns a set representing the intersection of s1 and s2.

(d) Write the function:

diffS :: (Ord a) => Set a -> Set a -> Set a

So that \textit{diffS} \ s1 \ s2 returns a set representing the set-difference of s1 and s2, which is precisely the elements contained in s1 that are not in s2.

(e) Write the function:

subseteq :: (Ord a) => Set a -> Set a -> Bool

So that \textit{subseteq} \ s1 \ s2 returns true whenever s1 is a subset of s2.

(f) Now, put all these in a module named sets, and test your functions. I would like you to submit either a haskell script or a set of instructions you run at the command prompt after loading your module that indicate success of each of your functions.

3. Extra credit: Define a function \texttt{subsequence} that takes two lists and returns the ascending list of indices at which the first list occurs as a subsequence of the second list. If there are multiple solutions, return the one with smallest sum of all indices. (Note there will always be one such solution and you will find it easily using the greedy approach.)

\texttt{subsequence :: Eq a => [a] -> [a] -> [Int]}

\begin{align*}
\text{subsequence "abcde" "abcbcdf" } & \Rightarrow [0, 1, 2, 5, 6] \\
\text{subsequence [9, 9, 7] [9, 7, 7, 9, 9, 7] } & \Rightarrow [0, 3, 5] \\
\text{subsequence "abc" "caccdbdca" } & \Rightarrow [1, 6, 8] \\
\text{subsequence "312" "1212313" } & \Rightarrow \text{error "subsequence does not exist"}
\end{align*}