

1. In a smooth  $m$ -manifold  $M$ , show every point  $p \in M$  has a chart  $(U, \varphi)$  with  $\varphi(p) = \mathbf{0}$  and  $\varphi(U) = B(\mathbf{0}, 1)$ , the open ball of radius 1 around  $\mathbf{0} \in \mathbb{R}^m$ .

**Solution:** Let  $(V, \psi)$  be any chart containing  $p$ . Suppose  $\psi(p) = \mathbf{x}$ . Let  $r > 0$  so that the open ball  $B(\mathbf{x}, r) \subset \psi(V)$  ( $\psi$  is a homeomorphism and  $V$  is open). Put  $U = \psi^{-1}(B(\mathbf{x}, r))$  and  $\varphi = \frac{1}{r}\psi - \mathbf{x}$ . Then  $(U, \varphi)$  is the desired chart.

2. Let  $f : M \rightarrow N$  be a smooth map of manifolds. Define the graph of  $f$  to be  $\Gamma(f) \subset M \times N$  as  $\Gamma(f) = \{(x, y) \in M \times N \mid f(x) = y\}$ . Show  $\Gamma(f)$  is a manifold.

**Solution:** For  $x_0 \in M$ , let  $(U, \varphi)$  be a chart for  $M$  with  $x_0 \in U$ , and let  $(V, \psi)$  be a chart for  $N$  with  $f(x_0) = y_0 \in V$ . Define  $W_{x_0} = \{(x, y) \in \Gamma(f) \mid x \in U \text{ and } y \in V\}$ . For  $(x, y) \in W_{x_0}$ , let  $\zeta_{x_0}(x, y) = (\varphi(x), \psi(y)) \in \mathbb{R}^{m+n}$ . If charts for  $x_1, x_2$  overlap, then  $\zeta_{x_2} \zeta_{x_1}^{-1} = (\varphi_{x_2} \varphi_{x_1}^{-1}, \psi_{x_2} \psi_{x_1}^{-1})$  is smooth since the component maps are smooth.

Finally, the map  $\Gamma(f) \rightarrow M$  given by  $(x, y) \rightarrow x$  is a homeomorphism (actually, it's a diffeomorphism), so  $\Gamma(f)$  is Hausdorff and paracompact since  $M$  is.

3. Define  $\sigma : M \times M \rightarrow M \times M$  by  $\sigma(x, y) = (y, x)$ . Show that  $\sigma$  is a diffeomorphism.

**Solution:** Fix  $(x, y) \in M \times M$ , and let  $(U, \varphi)$ ,  $(V, \psi)$  be charts on  $M$  containing  $x$  and  $y$  respectively. Then  $(U \times V, \varphi \times \psi)$  is a chart on  $M \times M$  containing  $(x, y)$ , and  $(V \times U, \psi \times \varphi)$  is a chart on  $M \times M$  containing  $(y, x)$ . In these coordinates,  $T\sigma$  is given by the matrix  $\begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix}$  which is nonsingular. This also shows  $\sigma$  is smooth, since in these coordinates all partials of  $\sigma$  are smooth (constant!) functions. The inverse mapping theorem says  $\sigma$  is locally a diffeomorphism, and because  $\sigma$  is one-to-one and onto,  $\sigma$  is a diffeomorphism.

Another approach, suggested by Rob: Show  $\sigma$  is smooth, either by a coordinate argument as above, or by realizing  $\sigma$  as a composition of other smooth maps. Then,  $\sigma^{-1} = \sigma$  is also smooth, and  $\sigma$  is a diffeomorphism directly by the definition.

4. Given points  $x_1, \dots, x_k \in M$ , and values  $v_1, \dots, v_k \in \mathbb{R}$ , show there is a smooth function  $f : M \rightarrow \mathbb{R}$  with  $f(x_i) = v_i$  for all  $i$ .

**Solution:** Let  $U_i$  be an open neighborhood containing  $x_i$  so that  $x_j \notin \bar{U}_i$  for  $j \neq i$ . Let  $V_i = U_i - \bigcup_{j \neq i} \bar{U}_j$ , so the  $V_i$  are disjoint open neighborhoods of the  $x_i$ . Finally, let  $W_i$  be an open neighborhood of  $x_i$  with  $\bar{W}_i \subset V_i$ . For each  $i$ , take a smooth cutoff function  $\varphi_i$  which vanishes on  $V_i - W_i$  and with  $\varphi_i(x_i) = 1$ . Extend each  $\varphi_i$  (by zero) to all of  $M$ , so that in particular  $\varphi_i(x_j) = 0$  for  $j \neq i$ . Let  $f = \sum_i v_i \varphi_i$ . Then  $f$  is smooth and  $f(x_i) = v_i$ .

5. In homogeneous coordinates on  $\mathbb{R}P^1$ , every point but  $[1 : 0]$  can be written as  $[x : 1]$ , and every point but  $[0 : 1]$  can be written as  $[1 : y]$ . Away from those two points, write  $\frac{\partial}{\partial x}$  in terms of  $\frac{\partial}{\partial y}$ .

**Solution:** The change of coordinates is given by  $x \rightarrow 1/x = y$ . This has derivative  $-1/x^2$ . Then  $\frac{\partial}{\partial x} \rightarrow \frac{-1}{x^2} \frac{\partial}{\partial y}$ , or  $\frac{\partial}{\partial x} = -y^2 \frac{\partial}{\partial y}$ .

6. On the torus  $\mathbb{T}^2 = S^1 \times S^1 = \{(e^{i\theta}, e^{i\phi})\}$ , define a map  $f : \mathbb{T}^2 \rightarrow \mathbb{T}^2$  by

$$f(e^{i\theta}, e^{i\phi}) = (e^{i(a\theta+b\phi)}, e^{i(c\theta+d\phi)})$$

where  $a, b, c, d$  are integers. Show that  $f$  is well defined, and is a diffeomorphism if  $ad - bc = \pm 1$ .

**Solution:** To see  $f$  is well defined, let  $\theta' = \theta + 2k\pi$  and  $\phi' = \phi + 2\ell\pi$ . Then

$$f(e^{i\theta'}, e^{i\phi'}) = (e^{i(a\theta+b\phi)+2\pi i(ak+b\ell)}, e^{i(c\theta+d\phi)+2\pi i(ck+d\ell)}) = f(e^{i\theta}, e^{i\phi})$$

since  $a, b, c, d$  are integers. Using  $\theta, \phi$  as local coordinates on  $\mathbb{T}^2$ ,  $Tf = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ . Note that the specific charts used will require  $\theta, \phi$  in some range of angles,  $(0, 2\pi)$  or  $(-\pi, \pi)$  for example, but that the matrix form of  $Tf$  is the same in all choices.  $Tf$  is nonsingular if  $ad - bc \neq 0$ , and so  $f$  is a local diffeomorphism by the inverse function theorem. When  $ad - bc = \pm 1$ ,  $f$  has an inverse given by the inverse matrix  $\pm \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$ . When  $ad - bc = 1$ , this means  $f^{-1}(e^{i\theta}, e^{i\phi}) = (e^{i(d\theta-b\phi)}, e^{i(-c\theta+a\phi)})$  and the  $-1$  case is similar. Then  $f$  is a diffeomorphism.