

# Shortest Path: Bellman-Ford Algorithm Shortest Path in a DAG

CSCI 3100

<pre>INITIALIZE-SINGLE-SOURCE(<math>G, s</math>) 1  <b>for</b> each vertex <math>v \in G.V</math> 2      <math>v.d = \infty</math> 3      <math>v.\pi = \text{NIL}</math> 4  <math>s.d = 0</math></pre>	<pre>RELAX(<math>u, v, w</math>) 1  <b>if</b> <math>v.d &gt; u.d + w(u, v)</math> 2      <math>v.d = u.d + w(u, v)</math> 3      <math>v.\pi = u</math></pre>
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Relaxation (compute estimates)

## The Bellman-Ford algorithm idea

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Given a graph  $G$  and a starting vertex  $s$

Apply "relaxation" to each vertex,  $v$ , until  $v.d = \delta(s, v)$

Whenever a smaller  $v.d$  is found, update the predecessor of  $v$ ,  $v.\pi$

Question: how do we know when  $v.d = \delta(s, v)$ ?

## Relaxation properties

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### Convergence property

- If  $p$  is a shortest path from  $s$  to  $v$  using an edge  $(u, v)$ , and
- if  $u.d = \delta(s, u)$  at any time prior to relaxing edge  $(u, v)$ ,
- then  $v.d = \delta(s, v)$  after edge  $(u, v)$  has been relaxed.

### Path relaxation property

- If  $p = \langle v_1, v_2, \dots, v_k \rangle$  is a shortest path from  $v_1$  to  $v_k$ , and we relax the edges of  $p$  in order  $(v_1, v_2)$ ,  $(v_2, v_3)$ ,  $\dots$ ,  $(v_{k-1}, v_k)$ , then  $v_k.d = \delta(v_1, v_k)$
- This property holds even if other relaxations are intermixed with the relaxation of edges of  $p$

## Bellman-Ford Algorithm

Line 1

$$O(|V|)$$

Lines 2-4

$$O(|V| \cdot |E|)$$

Lines 5-7

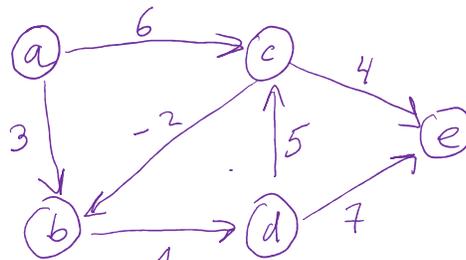
$$O(|E|)$$

**BELLMAN-FORD**( $G, w, s$ )

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1  INITIALIZE-SINGLE-SOURCE( $G, s$ )
2  for  $i = 1$  to  $|G.V| - 1$ 
3      for each edge  $(u, v) \in G.E$ 
4          RELAX( $u, v, w$ )
5  for each edge  $(u, v) \in G.E$ 
6      if  $v.d > u.d + w(u, v)$ 
7          return FALSE
8  return TRUE

```



$$s = a \quad |V| = 5$$

$$a.d = 0$$

$$b.d = \infty$$

$$c.d = \infty$$

$$d.d = \infty$$

$$e.d = \infty$$

$$(a, b): b.d = a.d + w(a, b) = 3; \quad b.\pi = a$$

$$(a, c): c.d = a.d + w(a, c) = 6; \quad c.\pi = a$$

$$(b, d): d.d = b.d + w(b, d) = 4; \quad d.\pi = b$$

$$(c, b): \text{---} \quad e.d = c.d + w(c, b) = 10; \quad e.\pi = c$$

$$(c, e): e.d = c.d + w(c, e) = 10; \quad e.\pi = c$$

$$(d, c): \text{---}$$

$$(d, e): \text{---}$$

## Key element of Bellman-Ford Algorithm

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How do we know that after  $|V|-1$  iterations, each edge has been relaxed as much as possible:

- $v.d = \delta(s, v)$  OR
- Path from  $s$  to  $v$  has a negative weight cycle

If shortest path exists, it will use at most  $|V|-1$  edges

Let  $v$  be any vertex reachable from  $s$  via a shortest path:

$(v_1, v_2, \dots, v_k)$ , where  $s=v_1$  and  $v=v_k$

Each of the  $|V|-1$  iterations relaxes  $|E|$  edges

Among edges relaxed at iteration  $i$  is edge  $(v_{i-1}, v_i)$

By the path relaxation property,  $v.d = v_k.d = \delta(s, v)$

## Shortest Path in a Directed Acyclic Graph (DAG)

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Shortest path in a DAG is well defined (no cycles, so no negative weight cycles)

Relax edges of a DAG in the topological sort order

## How do we get a topological sort order of vertices of a DAG?

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- A. Use Depth First Search
- B. Use Prim's algorithm
- C. Use Bellman-Ford algorithm
- D. Use Kruskal's algorithm
- E. Use priority queue

## Shortest Path in a DAG

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If DAG contains a path from vertex  $v$  to vertex  $u$  then

- $v$  precedes  $u$  in a topological sort

If we make one path over the vertices in the topological order

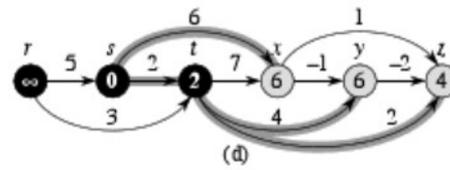
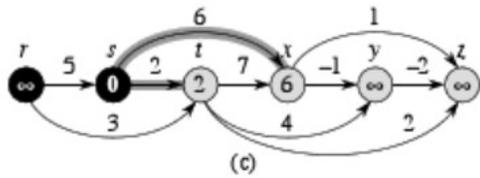
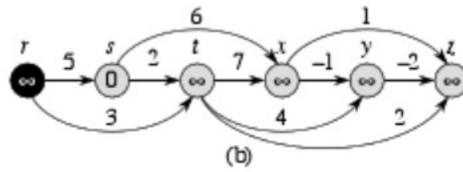
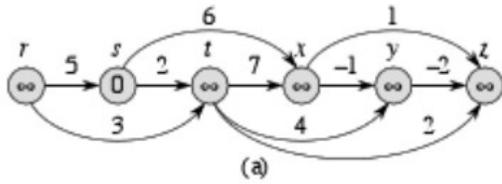
What is the running time of this algorithm?

$$O(|V| + |E|)$$

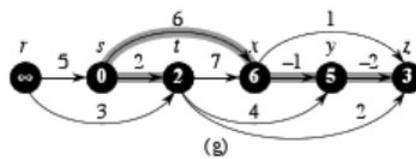
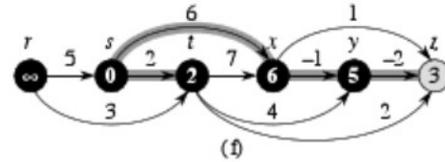
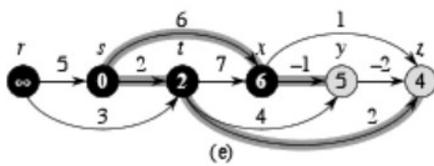
DAG-SHORTEST-PATHS( $G, w, s$ )

- 1 topologically sort the vertices of  $G$   $\rightarrow O(|V| + |E|)$
  - 2 INITIALIZE-SINGLE-SOURCE( $G, s$ )  $\rightarrow O(|V|)$
  - 3 for each vertex  $u$ , taken in topologically sorted order  $\rightarrow v$
  - 4     for each vertex  $v \in G.Adj[u]$   $\rightarrow E$
  - 5         RELAX( $u, v, w$ )
- $\left. \begin{array}{l} v \\ E \end{array} \right\} |V| + |E|$

## Example



## Example continued



If  $p = (v_1, v_2, \dots, v_k)$  is the shortest path from  $s=v_1$  to  $v=v_k$ , produced by Shortest Path in DAG algorithm, then

- A. Edges of  $p$  are relaxed in the order  $(v_1, v_2), (v_2, v_3), \dots, (v_{k-1}, v_k)$
- B. At iteration  $k$ ,  $v_k.d = \delta(s, v_k)$
- C. When relaxing edges adjacent to  $v_i$ ,  $v_i.d = \delta(s, v_i) < \infty$
- D. For any vertex  $v_i$   $(v_1, v_2, \dots, v_i)$  is the shortest path from  $s$  to  $v_i$
- E. All of the above are true

## Application of Shortest Path in DAG

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Determine a critical path in a schedule

Represent jobs as edges

Edge weights – time to perform each job

If edge  $(u, v)$  enters vertex  $v$  and edge  $(v, x)$  leaves vertex  $v$ , then job  $(u, v)$  must be done before job  $(v, x)$

A path through this DAG – a sequence of jobs that need to be performed in a particular order

In this context – a critical path is a longest path through the graph

Modify weights to be the negative of the time to perform each job and run Shortest Path in DAG algorithm